

ECE 388

Automatic Control

LAB 5

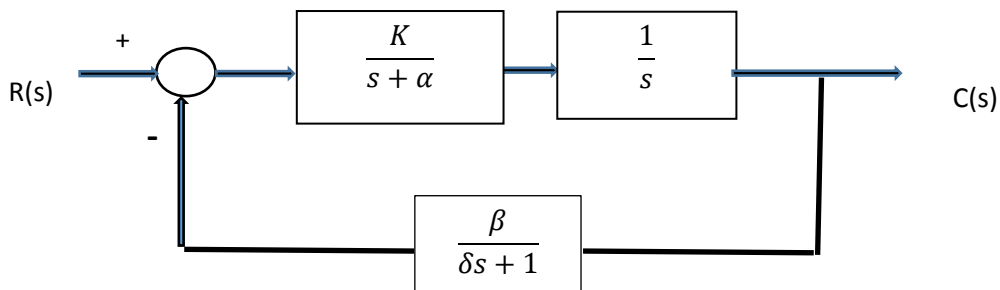
Mathematical Modeling of Physical Systems

**Objectives:** The objective of this exercise is to see the sensitivity of Transfer function due to parameter variations.

**List of Equipment/Software**

MATLAB, Simulink

**TASKS (by hand) :** For the given general feedback system



- 1) Determine the sensitivity of transfer function  $T(s)$  to small changes in  $K$

$$T(s) = \frac{C(s)}{R(s)}$$

- 2) Determine the sensitivity of transfer function  $T(s)$  to small changes in  $\alpha$
- 3) Determine the sensitivity of transfer function  $T(s)$  to small changes in  $\beta$
- 4) Determine the sensitivity of transfer function  $T(s)$  to small changes in  $\delta$
- 5) Show that your sensitivity calculations are logical if the nominal values of parameters used from the following table. For each case please state that the system is overdamped (**O**), underdamped (**U**) or critically damped (**C**). If it is instable, please note it.

Case	$K$	$\alpha$	$\beta$	$\delta$	O, U, or C
1	1	2	1	0	
2	1.5	2	1	0	
3	10	2	1	0	
4	-1	2	1	0	
5	1	10	1	0	
6	1	100	1	0	
7	1	-5	1	0	
8	1	2	10	0	
9	1	2	-1	0	
10	1	2	1	2	